



**DECALS**

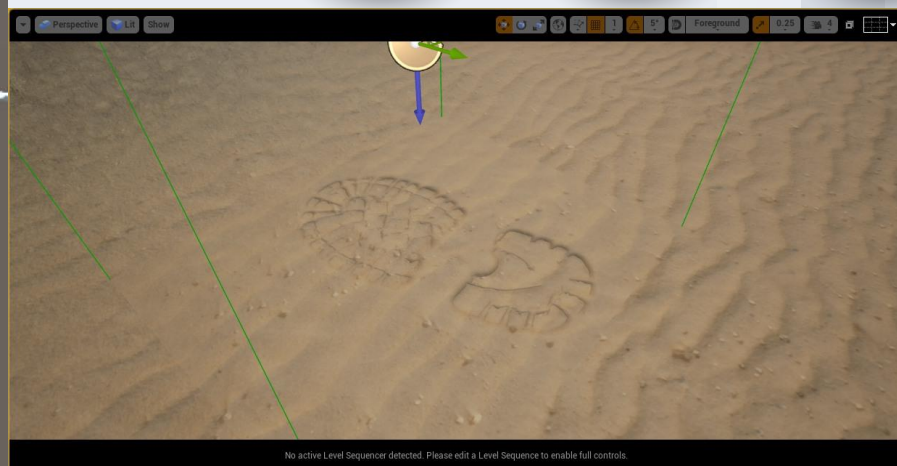
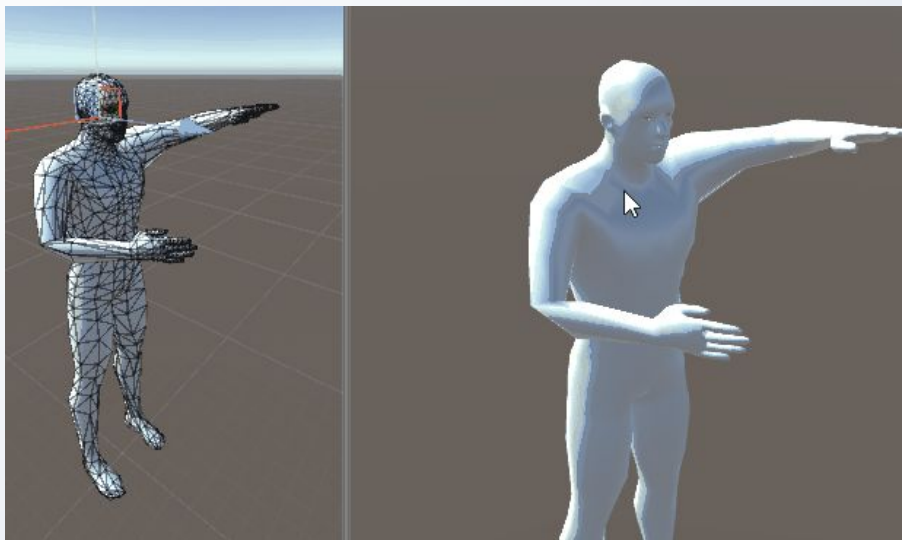
**BILLBOARDS**

**DEPTH OF FIELD**

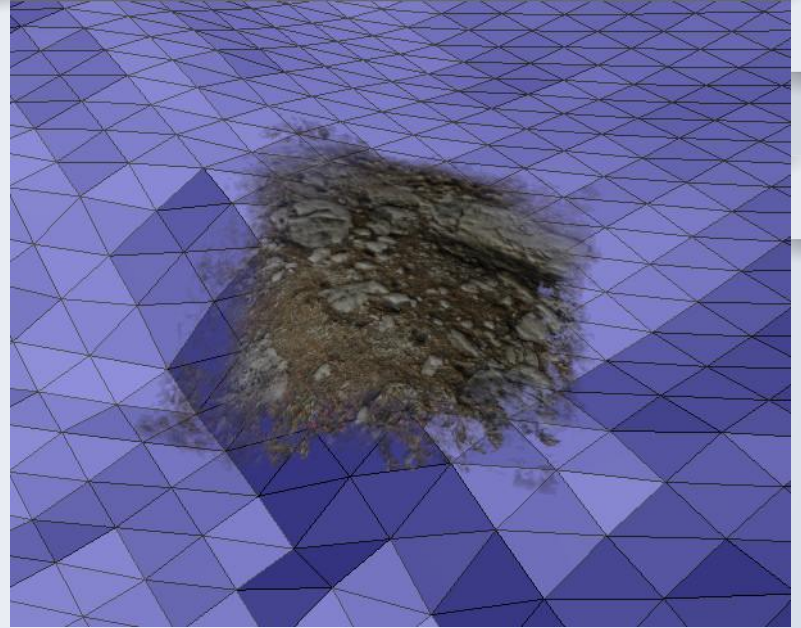
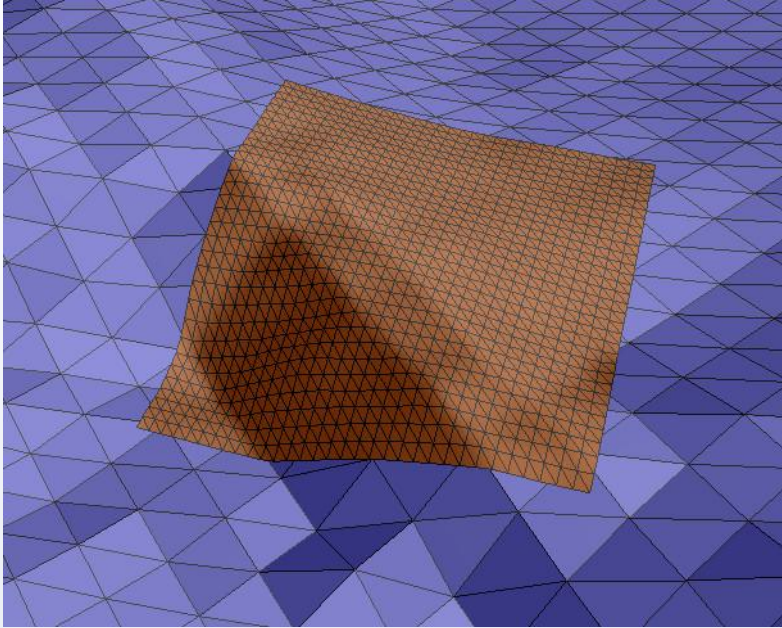
**MOTION BLUR**

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**DECALS**



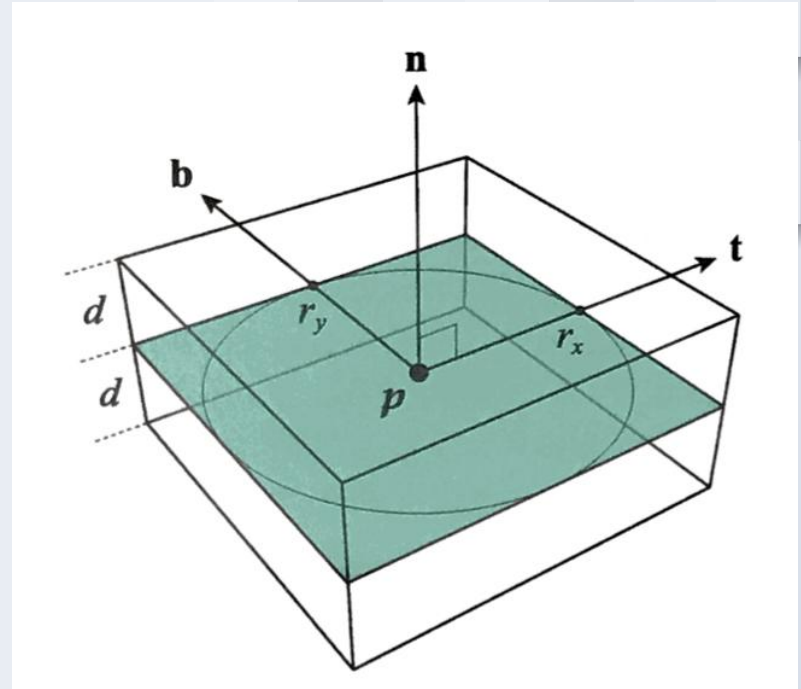
## Examples of decals



**Examples of decals**

## How does it work?

1. Get center of decal,  $\mathbf{p}$
2. Get normal of geometry,  $\mathbf{n}$
3. Compute tangent vector,  $\mathbf{t}$
4. Compute bitangent vector,  $\mathbf{b}$
5. Compute bounding box with distance  $\mathbf{d}$ .
6. Compute **decal clipping**.



## Focus on step #5 and #6

Compute  
bounding box  
with distance **d**.

Compute **decal  
clipping**.

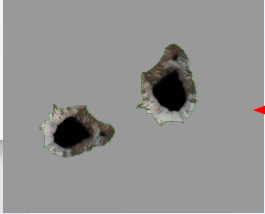
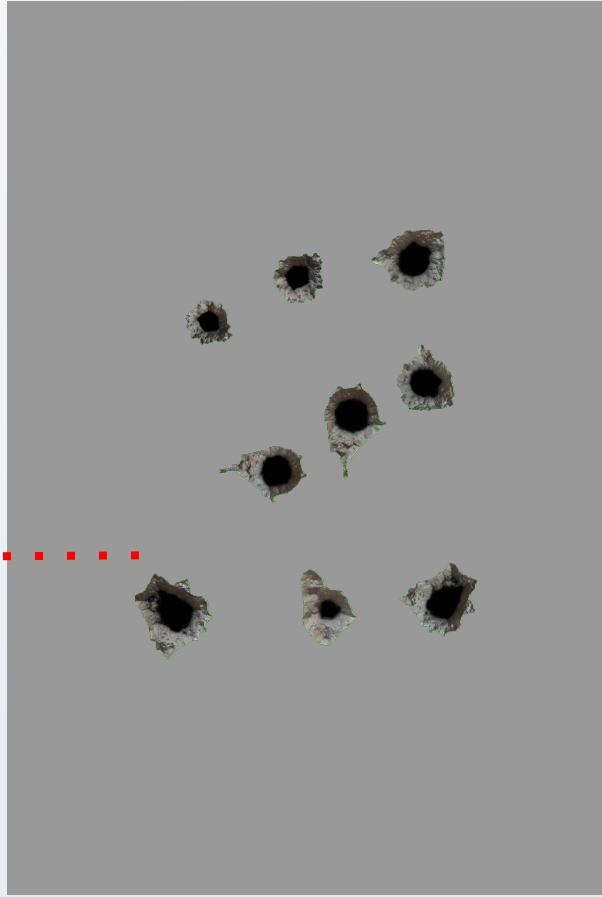
## Focus on step #5 and #6

Compute  
bounding box  
with distance **d**.

Compute **decal  
clipping**.



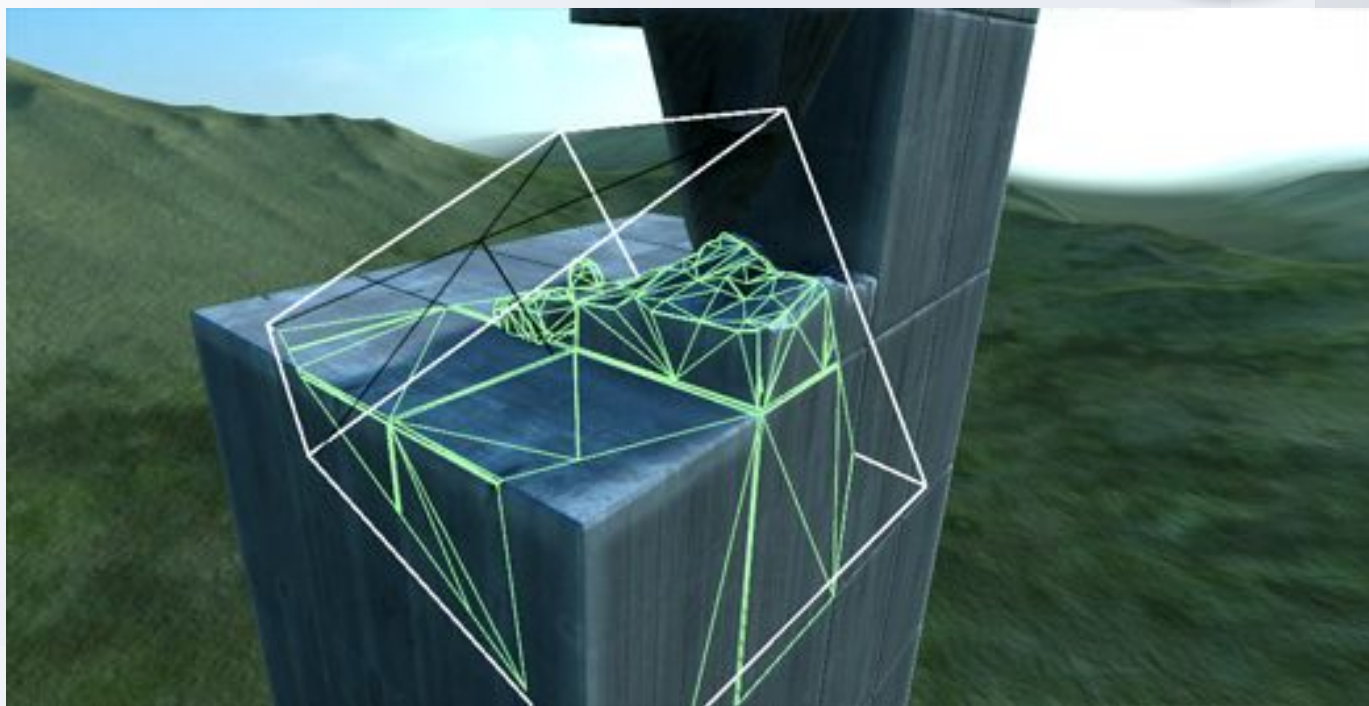


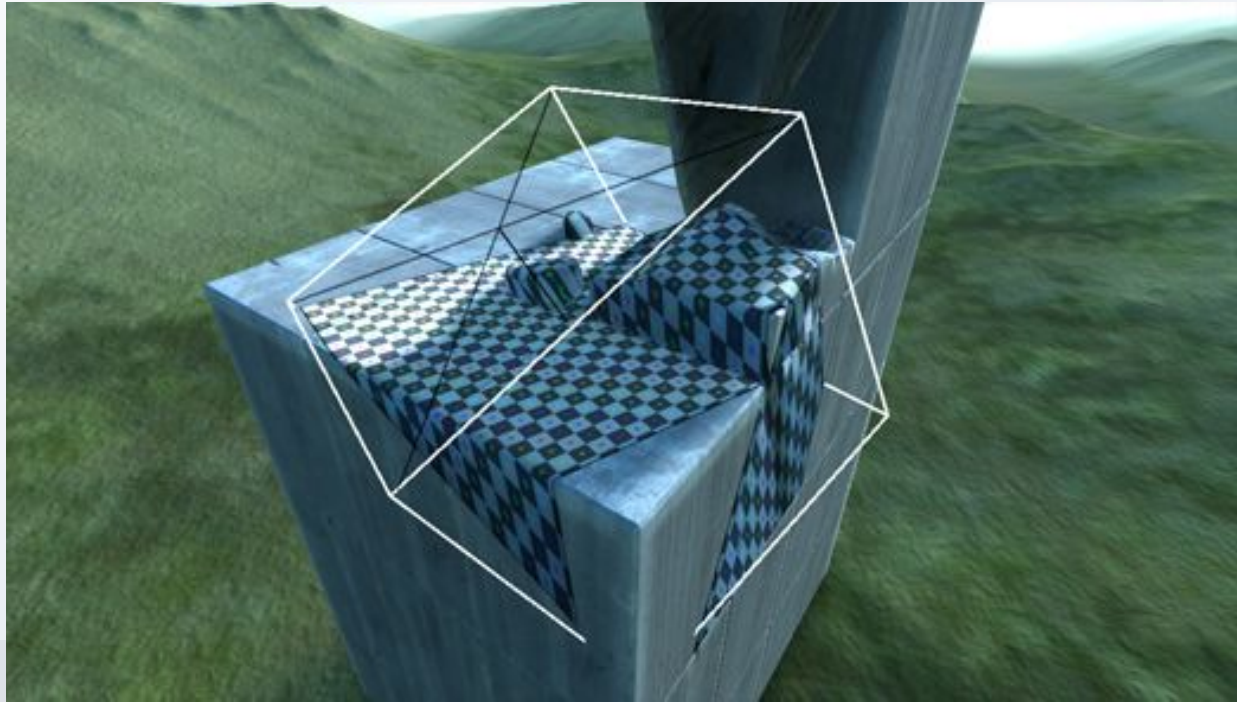


## Focus on step #5 and #6

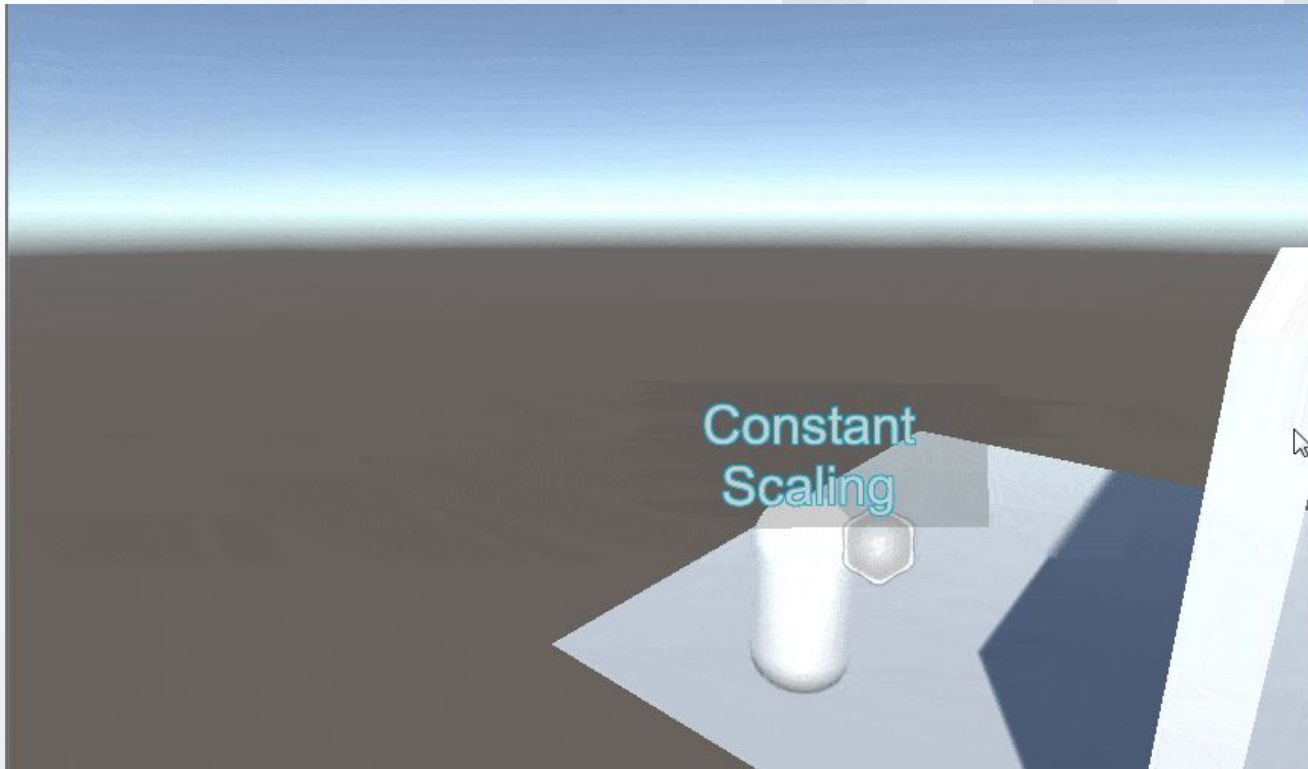
Compute  
bounding box  
with distance **d**.

Compute **decal  
clipping**.

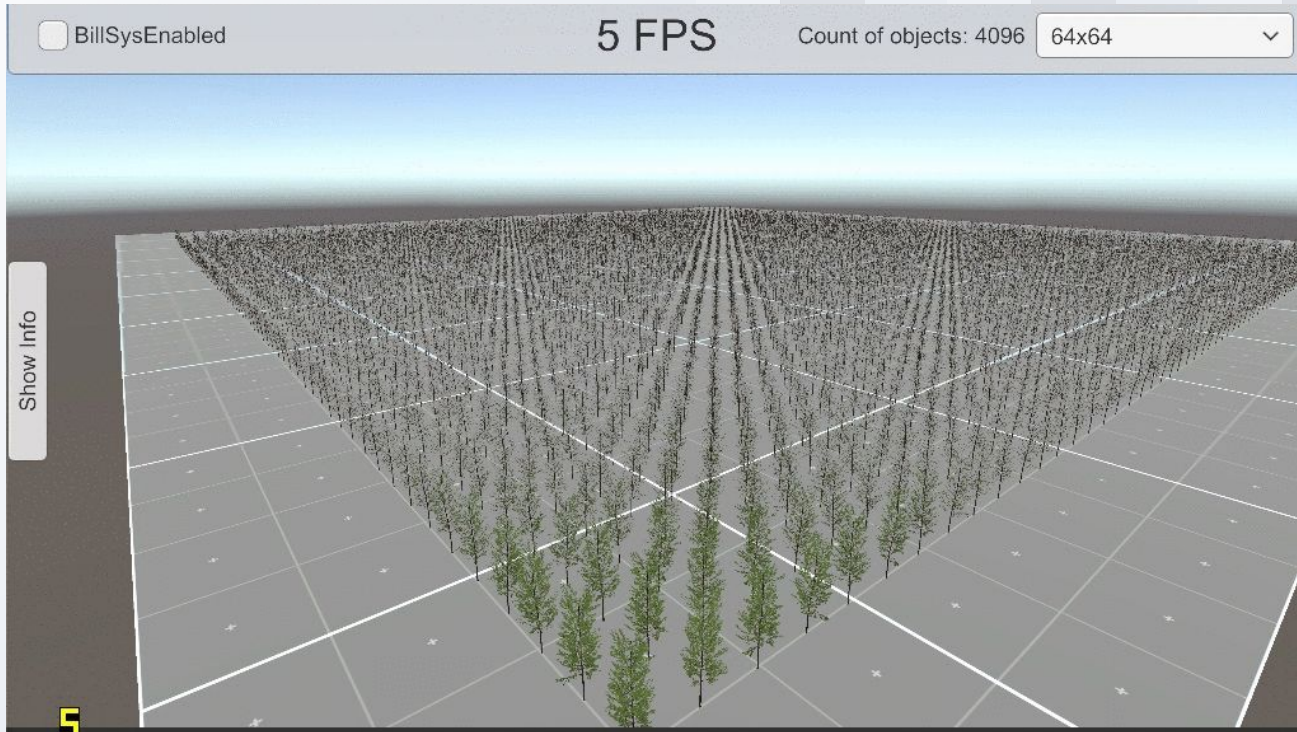




# **BILLBOARDS**

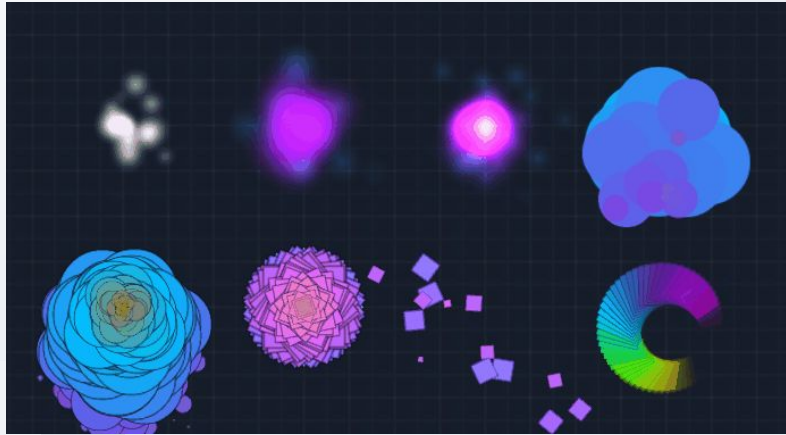


**Examples of billboards**

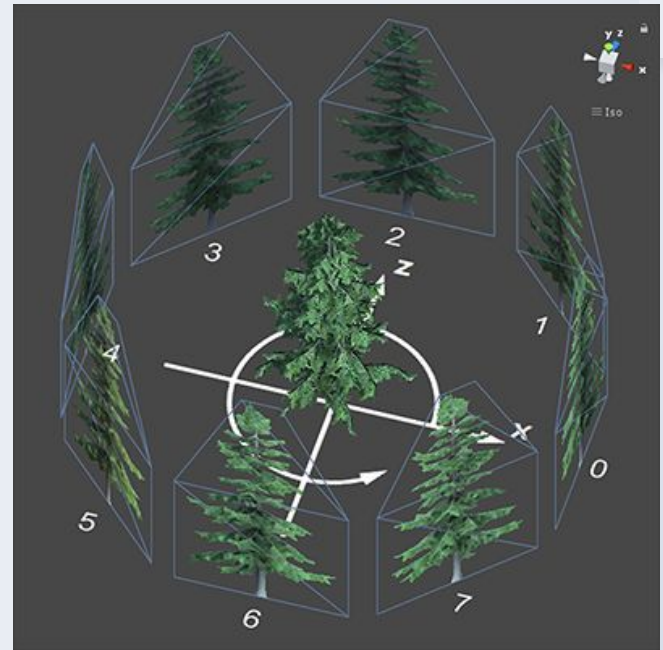


## Examples of billboards (impostors)

# Spherical

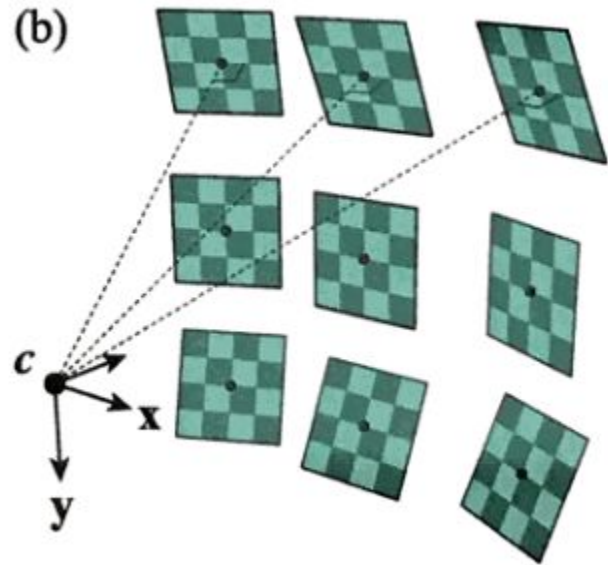
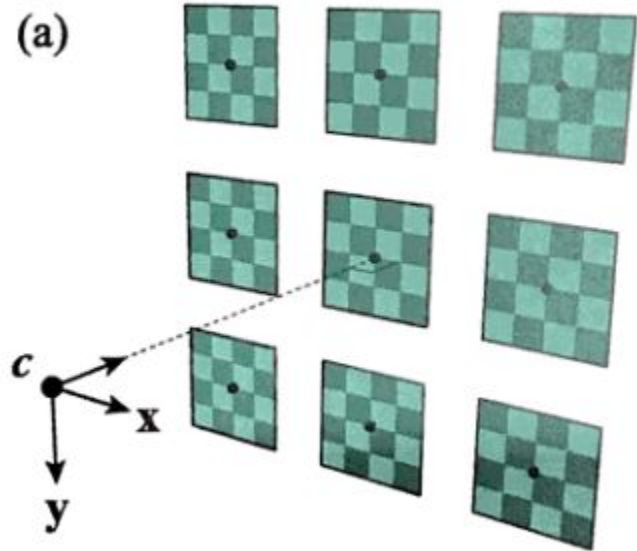


# Cylindrical

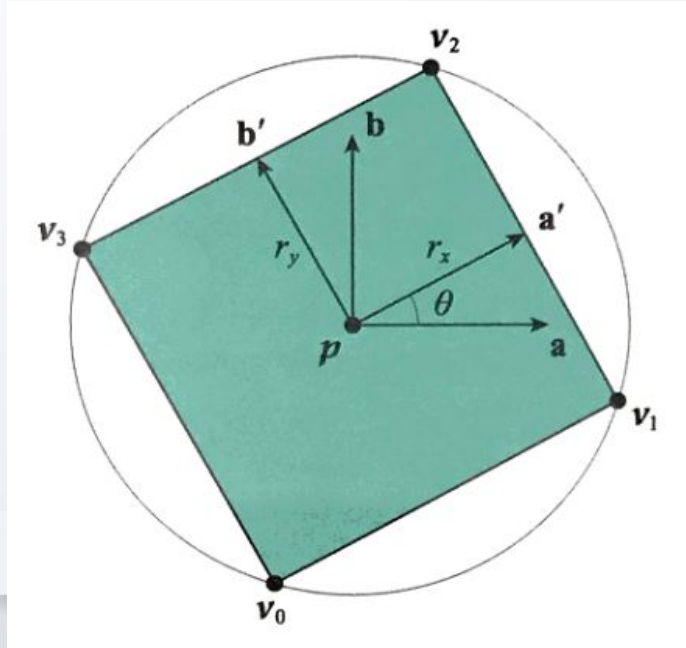




# Spherical billboards



# Spherical billboards

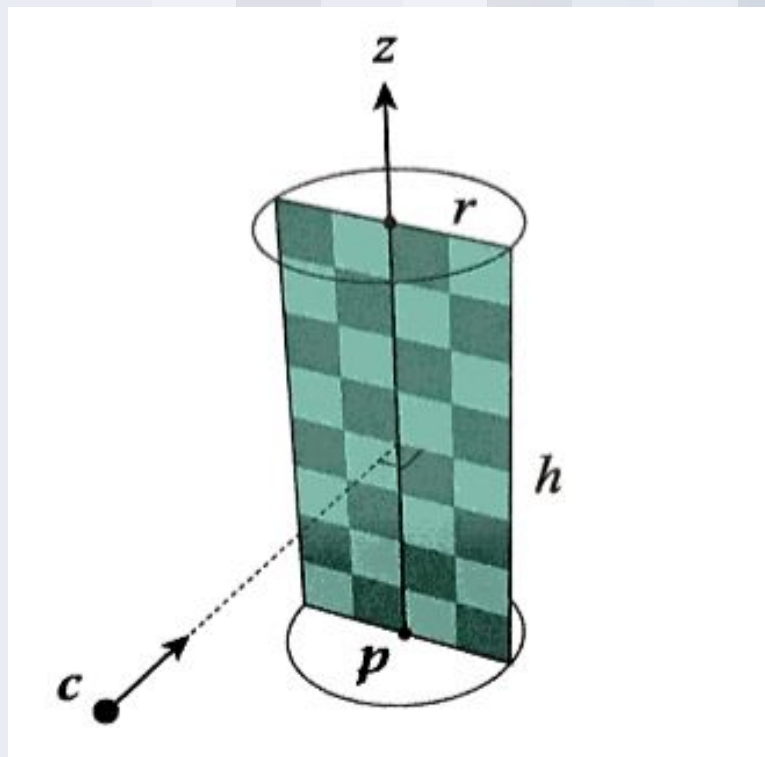


1. Get camera position,  $\mathbf{c}$ .
2. Set billboard's normal,  $\mathbf{n}$ , to face towards  $\mathbf{c}$ .
3. Calculate tangent vector,  $\mathbf{a}$ .
4. Calculate another tangent vector,  $\mathbf{b}$ .
5. Compute all **4 vertices** of the billboard.

## Cylindrical billboards

Computed the same way as a spherical billboard.

Except the tangent vector  $\mathbf{a}$  needs to be perpendicular to the z-axis.



# MOTION BLUR

The background features a grid of squares in various shades of gray, creating a motion blur effect. The squares are arranged in a pattern that suggests movement, with some squares appearing more prominent than others, giving the overall image a sense of depth and dynamic energy.

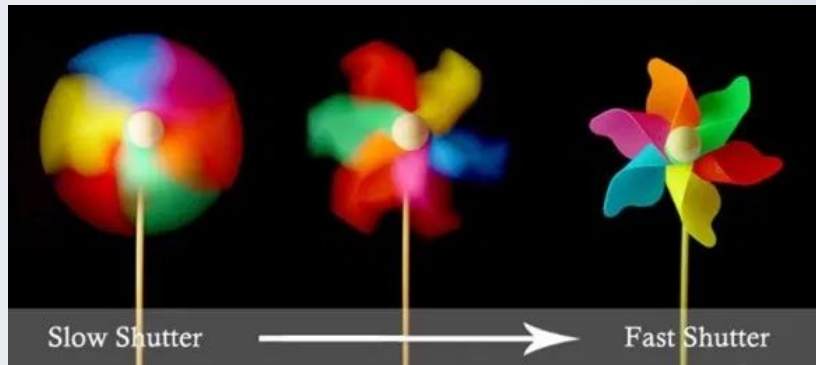
1. **What is it?**
2. **Implementation Methods**
3. **Velocity Buffer Implementation**
  - a. Velocity Buffer
  - b. Post-processing Blur

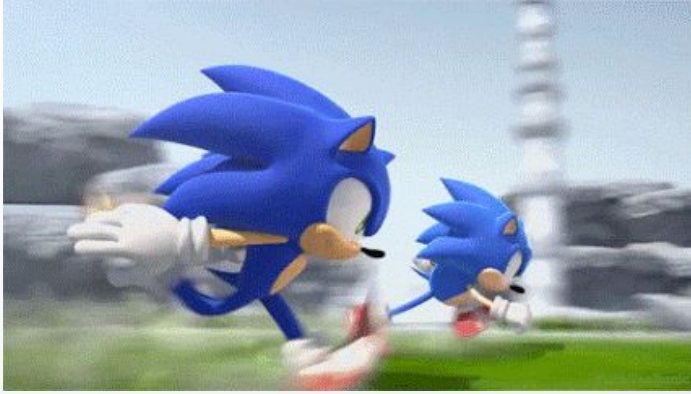


# 1. What is Motion Blur?

- ❑ Capturing images is light entering camera over a **time interval**

- ❑ **Not instantaneous**, so movement is recorded

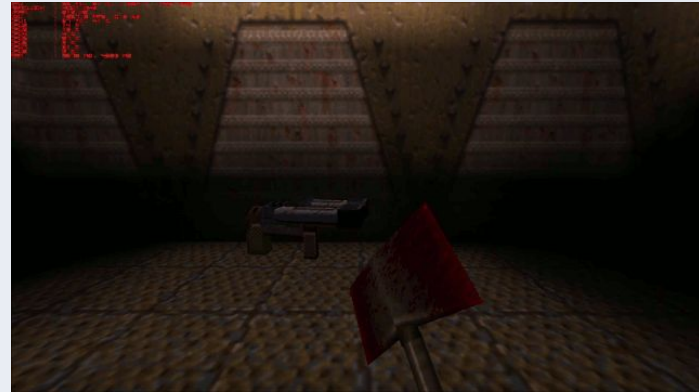
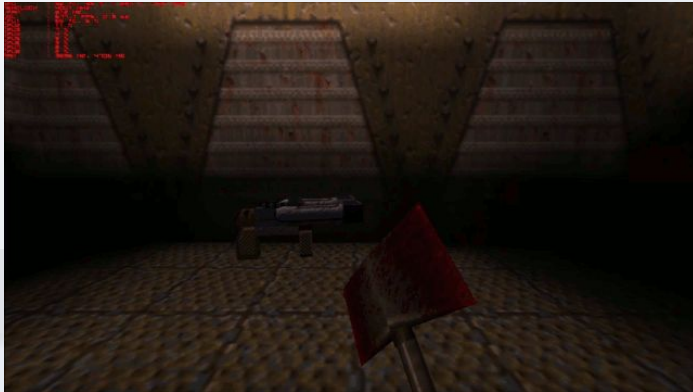




**Speed**



**Cinematic Effects**



**Smoothing**

## 2. Implementation Methods

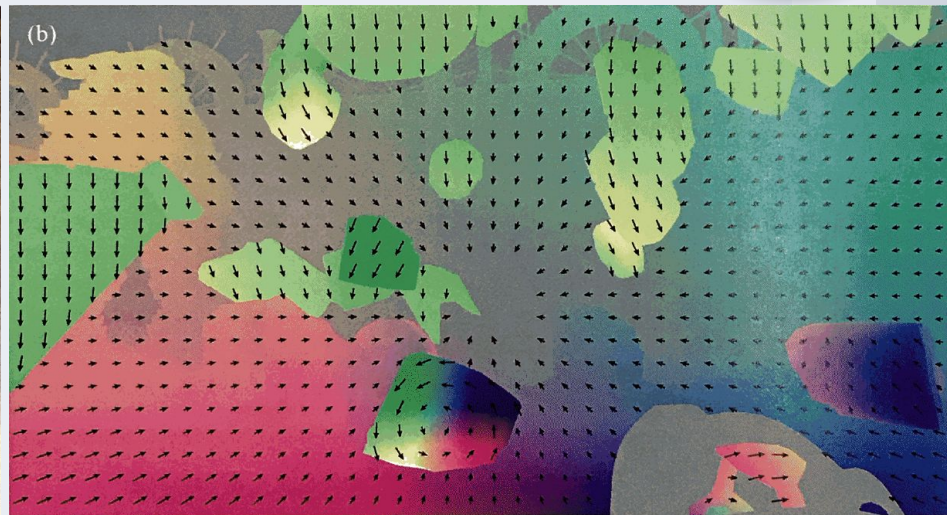
- ❑ Multiple ways to approach
  - ❑ Eg. Render many frames, average
- ❑ **Velocity Buffer Method**
  - ❑ Relatively inexpensive
  - ❑ Independent movement blurs properly



## Velocity Buffer Method

- ❑ Maintain a **Velocity Buffer**:
  - ❑ Holds a **velocity vector** for every pixel
  - ❑ Velocity vector represents how much that that surface will move between current/next frame

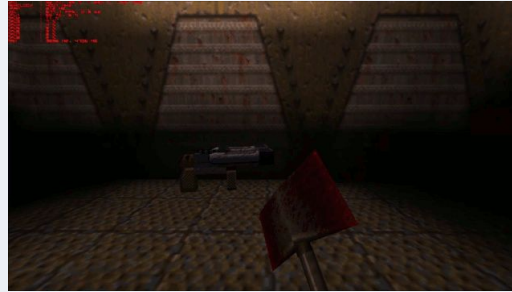
# The Velocity Buffer



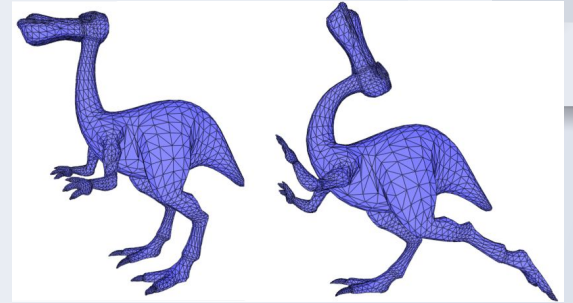
## Sources of Movement



Moving camera



Object transform



Mesh deformation

But the Velocity Buffer handles all three :)

## Getting Our Velocity Buffer Values

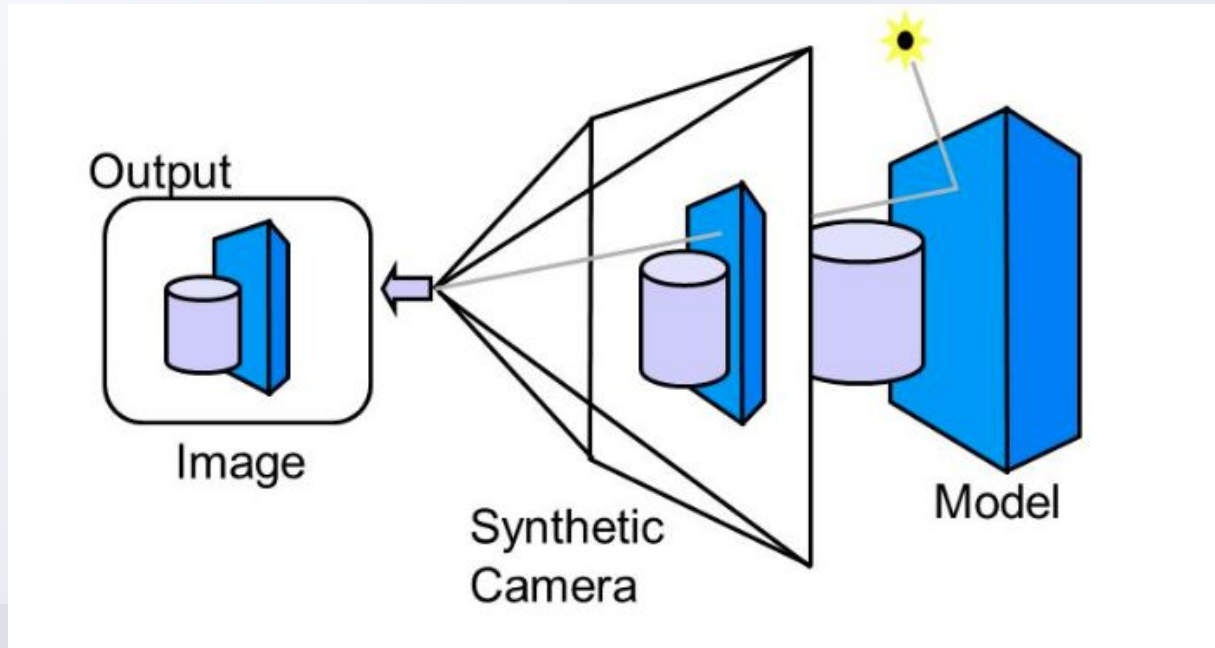
1. For each vertex
  - a. Compute positions for current/previous frame
  - b. Given positions, compute velocity
  - c. Store velocity in buffer

## Getting Our Velocity Buffer Values

$$\mathbf{P}_{\text{viewport}} = \mathbf{M}_{\text{viewport}} \mathbf{M}_{\text{projection}} \mathbf{M}_{\text{camera}}^{-1} \mathbf{M}_{\text{object}} \mathbf{p}_{\text{object}} \cdot$$

- $\mathbf{P}_{\text{object}}$  - object space vertex position
- $\mathbf{M}_{\text{object}}$  - object space  $\rightarrow$  world space
- $\mathbf{M}_{\text{camera}}$  - camera space  $\rightarrow$  world space
- $\mathbf{M}_{\text{projection}}$  - projection matrix (perspective)
- $\mathbf{M}_{\text{viewport}}$  - scales to viewport dimensions
- $\mathbf{P}_{\text{viewport}}$  - viewport space vertex position

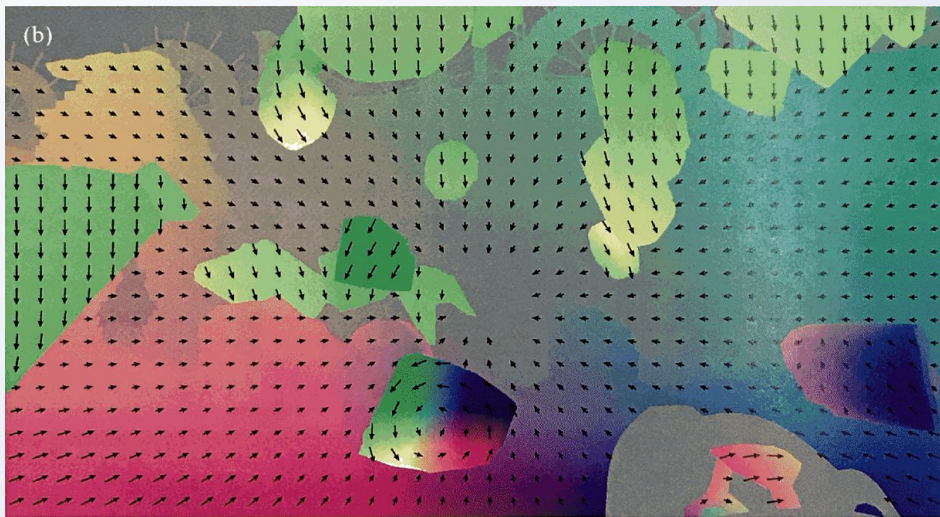
## Getting Viewport Positions



## Computing Velocity

- ❑ Computing velocity:  $v = \frac{d}{t}$
- ❑ The actual formula (p 361) is a little more complex
  - ❑ Scaling parameter
  - ❑ Normalized (time)
  - ❑ Clamped into [0, 1]

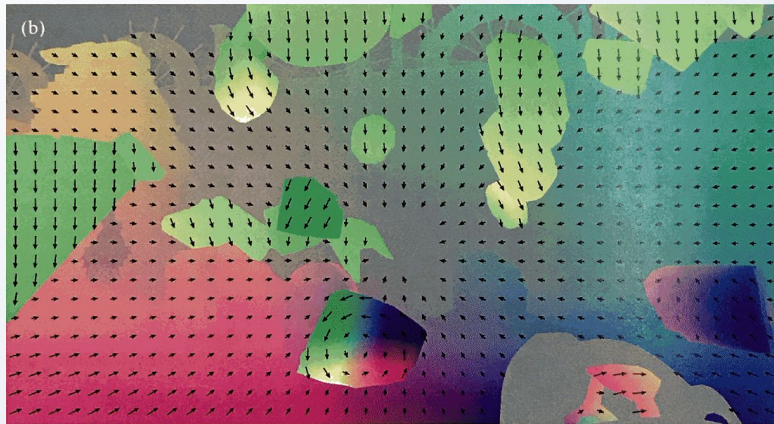
## Storing Velocity



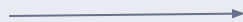
- ❑ Now **vertices** all have storable velocity values
- ❑ Velocities interpolated over triangles
- ❑ Every **pixel** has a storable velocity



# Blur Postprocessing



How do we use this...



...for this?

## Blur Postprocessing

- For each pixel:
  1. Reference pixel's velocity vector
  2. Read samples in +/- direction along vector
  3. Average color information of samples

## Blurring Sample Code

```
uniform TextureRect    colorBuffer;
uniform TextureRect    velocityBuffer;
uniform float          vstep;

float3 ApplySimpleMotionBlur(float2 pixelCoord)
{
    // Read color buffer and velocity buffer at center pixel.
    float3 color = texture(colorBuffer, pixelCoord).xyz;
    float2 velocity = texture(velocityBuffer, pixelCoord).xy * 2.0 - 1.0;

    // Add 8 more samples along velocity direction.
    for (int i = 1; i <= 4; i++)
    {
        float dp = float(i) * vstep;
        color += texture(colorTexture, pixelCoord + velocity * dp).xyz;
        color += texture(colorTexture, pixelCoord - velocity * dp).xyz;
    }

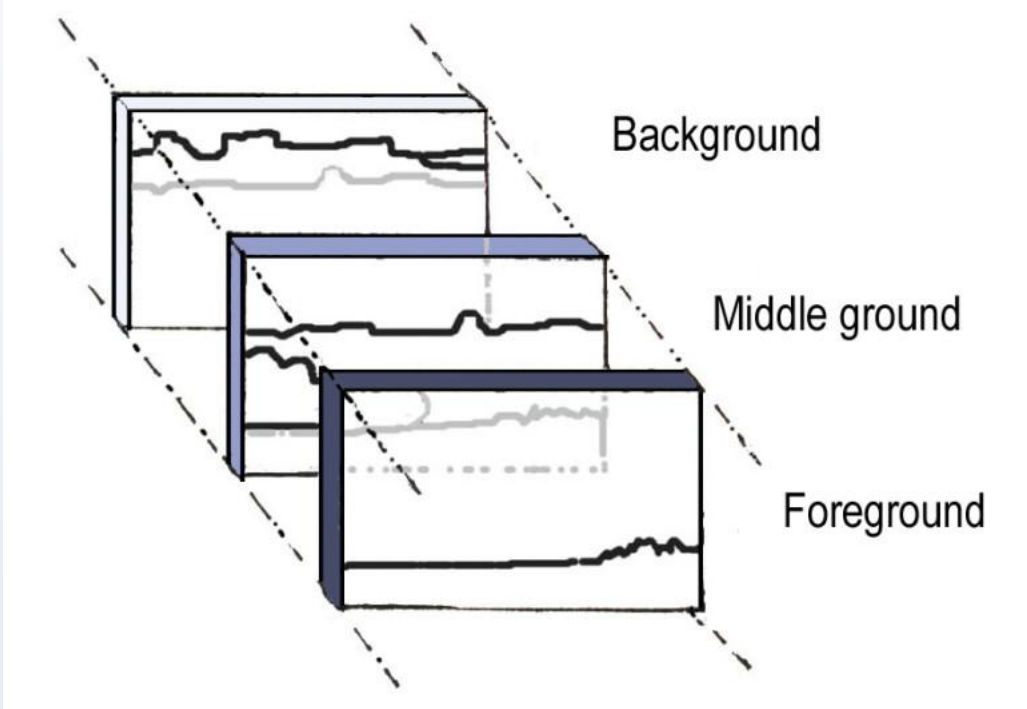
    // Return average of all samples.
    return (color * 0.1111111);
}
```

## Implementation Extras (Read the Book)



# DEPTH OF FIELD

# Where's the Focus



## Turning our Motion Blur Method into DOF

- ❑ For each vertex
  - ❑ Compute distance from camera
  - ❑ If vertex is in **midground, no blur**
  - ❑ Else, **blur**
    - ❑ Sample around pixel
    - ❑ Average color information

## Turning our Motion Blur Method into DOF

- ❑ For each vertex
  - ❑ Compute distance from camera
  - ❑ If vertex is in midground, no blur
  - ❑ Else, **blur**
    - ❑ Sample around pixel **with sample radius dependent on distance**
    - ❑ Average color information



## Further Reading

### [GPU Gems Chapter 23](#)

- ❑ Explains phenomenon in physics
- ❑ Overviews a couple implementations